## Example 5.3 Effect of girders on the raft rigidity

### **1** Description of the problem

Ribbed raft may be used for many structures with heavy loads or large spans, if a flat level for the first floor is not required. Consequently, concrete is reduced. Such structures are silos and elevated tanks. In spite of this type of foundation has many disadvantages if used in normally buildings, it still is used by many designers. Such disadvantages are the raft needs deep foundation level under the ground surface, fill material on the foundation to make a flat level and an additional slab on the fill material to construct the first floor. The use of the ribbed raft relates to the simplicity of analysis by hand calculations.

First, both of the two rafts with and without ribs are clearly save and correct, but there is still a question, whose one of the two types is more rigid? To answer this question the following example is presented.

Consider the foundation of an elevated tank may be designed for both types of foundations. The foundation has the dimensions of 20 [m]  $\times$  20 [m] and transmits equal loads for all 25 columns, each of 1000 [kN]. The loads give average contact pressure on soil  $q_{av} = 62.5$  [kN/m<sup>2</sup>]. Columns are equally spaced, 4 [m] apart, in each direction as shown in Figure 5.14.



Figure 5.14 General plan of rafts

The analysis of the foundation is carried out to study the effects of soil types, rigidity of girders and slabs. A detail description of each parameter is presented as follows.

### 2 Soil

Three subsoil models are considered:

- i) Simple assumption model (conventional method) that assumes linear distribution of contact pressure on the bottom of the slab. The model considers no interaction between the raft and the subsoil
- ii) *Winkler*'s model that represents the subsoil by isolated springs
- iii) Layered model that considers the subsoil as continuum medium

The raft resting on a soil layer of 20 [m] is equal to the raft side, overlying a rigid base. The soil types are represented by the modulus of elasticity  $E_s$ , for layered model, which yields modulus of subgrade reaction  $k_s$  for *Winkler*'s model. Table 5.1 shows the different soil types examined in this example according to the soil properties  $E_s$  and  $k_s$ . *Poisson*'s ratio is taken  $v_s = 0.3$  for all soil types.

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$E_s$ [kN/m <sup>2</sup> ]	5000	10000	15000	20000	25000	30000	35000	40000	45000	50000
<i>ks</i> [kN/m <sup>3</sup> ]	583	1166	1749	2332	2915	3498	4081	4664	5247	5830

## **3** Concrete material

The parameters of raft material are *Young*'s modulus  $E_b = 2 \times 107$  [kN/m<sup>2</sup>], *Poisson*'s ratio  $v_b = 0.25$  and shear modulus  $G_b = 1 \times 107$  [kN/m<sup>2</sup>].

## 4 Girders

A rectangular cross section is used for the girders with constant width of 0.40 [m]. The effect of girder rigidity is studied by varying its depth  $d_g$ . Influence of the effective flange width of the slab on the moment of inertia of the girder is neglected.

## 5 Slab

For different chosen values of girder depth  $d_g$ , the corresponding values of slab thickness are 0.25, 0.30, 0.35, 0.40, 0.45 and 0.50 [m].

### 6 Analysis and discussion

The study of the raft is done for both cases, with and without girders. First the foundation is designed using working stress method according to the Egyptian code of practice (ECP), for concrete and steel grades  $f_c = 60 \, [\text{kg/cm}^2]$  and  $f_s = 1400 \, [\text{kg/cm}^2]$  respectively. The design is carried out using the classical method without interaction between the soil and the foundation. Through this design the dimensions of the raft with girders are slab thickness  $d_s = 0.25 \, [\text{m}]$ , girder depth  $d_g = 0.85 \, [\text{m}]$  and girder width  $b_g = 0.40 \, [\text{m}]$ , while the thickness for the flat raft is  $d_r = 0.55 \, [\text{m}]$ . The analysis is focused on the layered Continuum model, because it is more realistic than *Winkler*'s model for simulation of most soil types.

### 6.1 System rigidity

A good advantage of the foundation rigidity analysis, proposed by *El Gendy* (1998), is the possibility to find the system rigidity of rafts having any shape, such as ribbed rafts, considered in this example. Therefore, series of computations are carried out for many variables with the parameter  $k_r$  obtained at the center of the raft, to compare between the system rigidity of the two types of rafts with and without girders.

Figure 5.15 shows the parameter  $k_r$  with the raft thickness  $d_s$  in case of the flat raft while Figure 5.16 shows the parameter  $k_r$  with girder depth  $d_g$  at different slab thickness in case of the ribbed raft. Both of the two figures are considered for soil of  $Es = 10000 \text{ [kN/m^2]}$ .



<u>Figure 5.15</u> Parameter  $k_r$  with raft thickness at the center of the raft ( $E_s = 10000 \text{ [kN/m}^2\text{]}$ )

## 3

From these figures, it can be found that the flat raft of thickness  $d_r = 0.55$  [m] gives parameter  $k_r = 60$  [%] while the raft of slab thickness  $d_s = 0.25$  [m] and girder depth  $d_g = 0.85$  [m] gives parameter  $k_r = 52$  [%]. This means the ribbed raft designed by the classical method has rigidity less than that of the flat raft designed also by the same method. The ribbed raft, which gives parameter  $k_r = 60$  [%] equals to that of the flat raft, can be easily obtained from Figure 5.16. In which may be had one of the following dimensions in Table 5.2.

Slab thickness <i>d<sub>s</sub></i> [m]	0.25	0.30	0.35	0.40	0.45	0.50
Girder depth $d_g$ [m]	1.25	1.20	1.15	1.10	0.90	0.75

<u>Table 5.2</u> Dimensions of ribbed rafts, which give parameter  $k_r = 60$  [%]

From Figure 5.16, it can be concluded that the slab thickness  $d_s$  for rafts with a small girder  $d_g$  has great influence on the system rigidity. This influence decreases by increase the girder depth  $d_g$  until  $d_g = 2.0$  [m], then becomes constant. This means that the girders of depth  $d_g > 2.0$  give most the system rigidity.



<u>Figure 5.16</u> Parameter  $k_r$  with girder depth at the center of the raft ( $E_s = 10000 \text{ [kN/m^2]}$ )

To check the system rigidity of the rafts with and without girders at different soil types, the parameter  $k_r$  for three selected rafts is plotted with the soil modulus  $E_s$  as shown in Figure 5.17.

The three rafts are:

Raft 1	flat raft of thickness $d_r = 0.55$ [m]
Raft 2	ribbed raft with slab thickness $d_s = 0.25$ [m] and girder depth $d_g = 0.85$ [m]
Raft 3	ribbed raft with slab thickness $d_s = 0.25$ [m] and girder depth $d_g = 1.25$ [m]

Figure 5.17 shows that the rafts 1 and 3 that have the same system rigidity at soil type  $E_s = 10000$  [kN/m<sup>2</sup>] have also the same system rigidities for all soil types. The range of the difference in  $k_r$  of raft 2 and raft 1 (or raft 3) is 20 [%] to 5 [%] for weak soil of  $E_s = 5000$  [kN/m<sup>2</sup>] to medium soil of  $E_s = 20000$  [kN/m<sup>2</sup>]. This difference decreases slowly for  $E_s > 20000$  [kN/m<sup>2</sup>] with increase of  $E_s$  until stiff soil of  $E_s = 45000$  [kN/m<sup>2</sup>], then  $k_r$  of raft 2 becomes identical with that of raft 3.

To show the influence of the soil types on the system rigidity of ribbed rafts, the parameter  $k_r$  is plotted with the girder depth at different soil types as shown in Figure 5.18. The raft has 0.25 m slab thickness. From Figure 5.18, it can be noted that, the system rigidity of raft on weak soil increases quickly rather than that of raft on stiff soil with increase of girder depth. At a small depth  $d_g$ , the difference in  $k_r$  of raft on weak soil and that of raft on stiff soil is small. This difference increases slowly until depth  $d_g = 1.75$ , then becomes nearly constant for the other depths more than 1.75 [m].



# Soil modulus $E_s$ [kN/m<sup>2</sup>]

<u>Figure 5.17</u> Parameter  $k_r$  with soil modulus  $E_s$  at the center of the raft



Figure 5.18 Parameter  $k_r$  with girder depth at different soil types at the center of the raft

#### 6.2 Effect of girders on differential settlement between columns

The effects of the girder rigidity and the soil types on differential settlement are studied by comparing the differential settlement between central column cc and its adjacent column ca for the flat raft (raft 1) and ribbed rafts (rafts 2, 3).

Figure 5.19 shows the differential settlement  $\Delta f$  with the soil rigidity represented by its modulus of elasticity  $E_s$ . From Figure 5.19, it can be found that the differential settlement  $\Delta f$  decreases quickly with the increase of  $E_s$  from  $E_s = 5000$  [kN/m<sup>2</sup>] to 10000 [kN/m<sup>2</sup>], then decreases slowly with the increase of  $E_s$  from 10000 [kN/m<sup>2</sup>] to 50000 [kN/m<sup>2</sup>] for both raft types. This figure indicates also that the differential settlement  $\Delta f$  for ribbed raft coincides with that of flat raft if the two types have the same rigidity (rafts 1 and 3) for all soil types. It is clear that the ribbed raft designed by classical method (raft 2) has differential settlement higher than that of rafts with and without girders (rafts 1 and 3), which have the same rigidity in case of weak soil. The increasing in differential settlement for raft 2 reaches 33 [%] to 14 [%] compared with those of rafts 1 and 3 in cases of soils have  $E_s = 5000$  [kN/m<sup>2</sup>] and  $E_s = 10000$  [kN/m<sup>2</sup>] respectively. However, for  $E_s$  greater than 25000 [kN/m<sup>2</sup>] until for stiff soil the differential settlement for raft 2 becomes less than that of rafts 1 and 3.



<u>Figure 5.19</u> Differential settlement  $\Delta f$  between columns with soil modulus  $E_s$ 

## 6.3 Effect of girders on contact pressure

The contact pressure under the ribbed rafts (raft 2 and 3) at section I-I for two soil types, weak and stiff, are compared with that of flat raft (raft 1).

The soil modulus for weak soil is  $E_s = 5000 \text{ [kN/m^2]}$  while for stiff soil is  $E_s = 50000 \text{ [kN/m^2]}$  in case of layered model. The corresponding modulus of subgrade reactions for these two soil types are  $k_s = 583 \text{ [kN/m^3]}$  and  $k_s = 5830 \text{ [kN/m^3]}$  for weak and stiff soil respectively in case of *Winkler*'s model.

Figure 5.20 shows the distribution of contact pressure at section I-I for *Winkler*'s model, while Figure 5.21 shows the distribution for layered model. The contact pressure according to the conventional method is plotted at the same figures. As the contact pressure distribution is similar to that of settlement distribution for *Winkler*'s model. Therefore, Figure 5.20 shows also the settlement at section I-I multiplied by the modulus  $k_s$ .

The effect of girders on the contact pressure is clear along the rafts for both *Winkler*'s and layered models. Such effect is very remarkable for weak soil, where the presence of girders increases the contact pressure under the girders. On the other hand, the girders decrease this contact pressure in the middle of the panels. Other figures, not included, show that the presence of girders leads to negative pressure at the corner of the raft in case of layered model for raft 2 of the less rigidity. The contact pressure of ribbed raft locates within the average range that of flat raft, if the two types have the same rigidity (rafts 1 and 3). This is obvious for stiff soil where may be coinciding with it. For the conventional method, the effect of girders plays no role on the contact pressure where is constant for all soil types and equal to the average load on the raft.







Figure 5.21 Contact pressure at section I-I for layered model

*x* [m]